

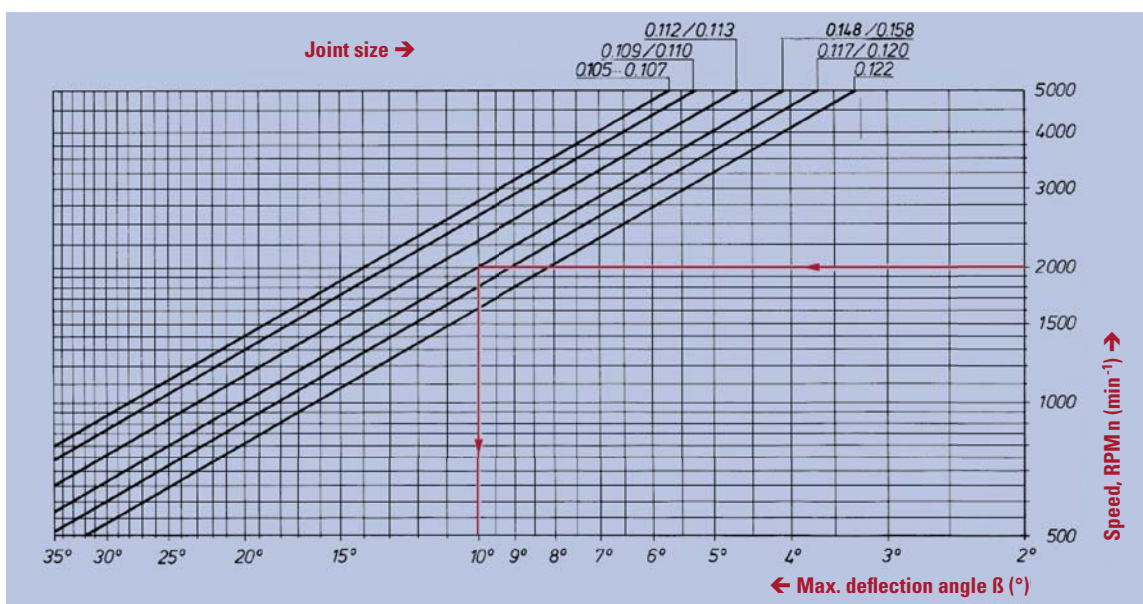
### 6.7 RPM and deflection angle

As shown in 2.3 by taking certain precautions, a constant output can be obtained on a universal driveline. The center part, however, still retains a non-uniform motion; it is subjected twice per revolution to an acceleration and deceleration. The resulting acceleration torque caused this way is a function of the mass moment of inertia of the driveline's

center part as well as of rpm and deflection angle. When regarding smoothness of operation and wear, the product of rpm and deflection angle should not be too high. For use in general mechanical engineering, appropriate guide values can be taken from the diagram below, which is designed for universal drivelines having a standard tubing of up

to 1500 mm length.

For vehicle drive trains, these guide values must often be exceeded. Here, at most, up to 1.5 times of the diagram value can be permitted.



### 6.8 Critical speeds

As shown in 5.1, the center part of the angled driveline, when transmitting torque, is being stressed periodically in bending by additional moment  $M_{Z1}$ . This incites the center part to vibrate. If the frequency of this bending vibration approaches the natural frequency of the driveline, maximum stress in all components, buckling of the shaft and development of noise will result.

To avoid this, long and fast running drivelines must be checked for critical bending vibration speeds. The critical, first order bending vibration speed of a driveline employing tubing can be roughly calculated as follows:

$$n_{kr} \approx 1,21 \cdot 10^8 \frac{\sqrt{D^2 + d^2}}{L^2} \quad [\text{min}^{-1}]$$

D = Tubing-outside diameter [mm]  
 d = Tubing-inside diameter [mm]  
 L = Center part length in [mm]

Drivelines are used in the subcritical zone only. For reasons of safety, it must be ensured that the maximum operating speed is far enough away from its system's resonance (critical) speed. Therefore, the following applies:

$$\text{Max. Operating Speed } n_{\text{max}} \approx 0,65 \cdot n_{\text{cr}} [\text{RPM}]$$